

Estimating intratumoral heterogeneity from spatiotemporal data

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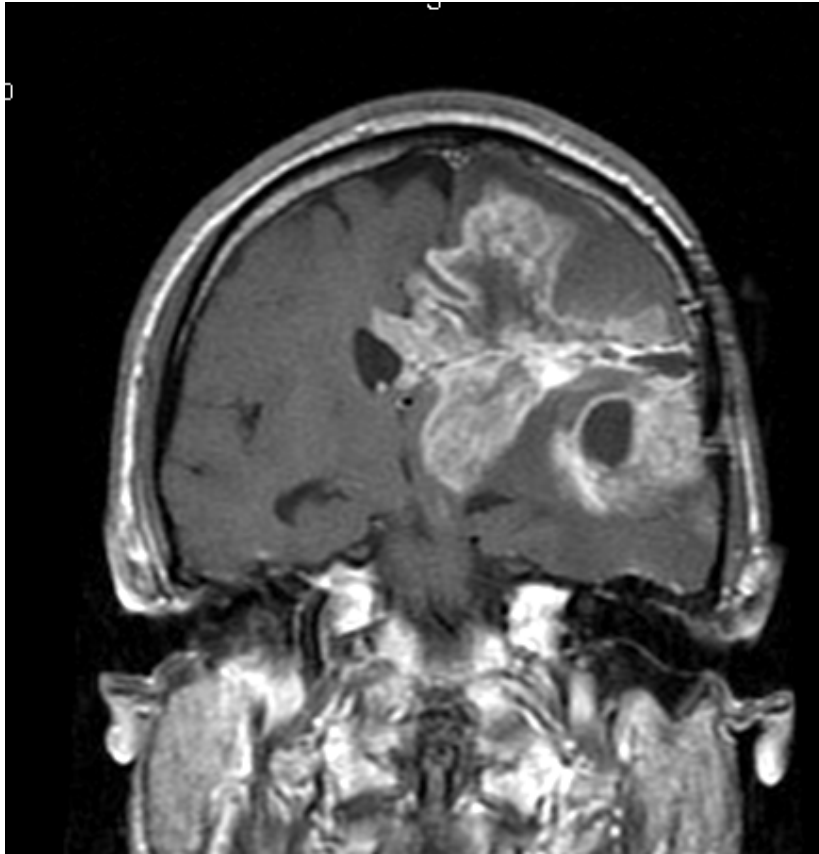
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November 28, 2018

BIRS-CMO Workshop: Mathematical Challenges in the Analysis of Continuum Models
for Cancer Growth, Evolution and Therapy

Funding: NSF Math Biology (DMS-1514929)

Glioblastoma Multiforme (GBM)

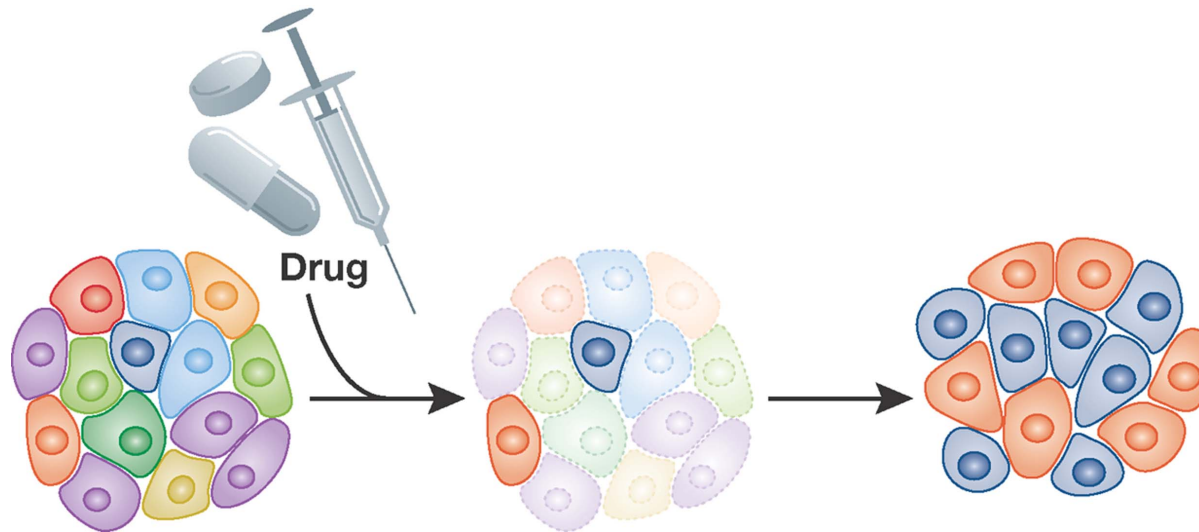


Sagittal cross-section of human brain with GBM

GBM is a deadly primary brain tumor characterized by:

- Phenotypic heterogeneity
- Low survivability
- Low response to treatment

Importance of heterogeneity

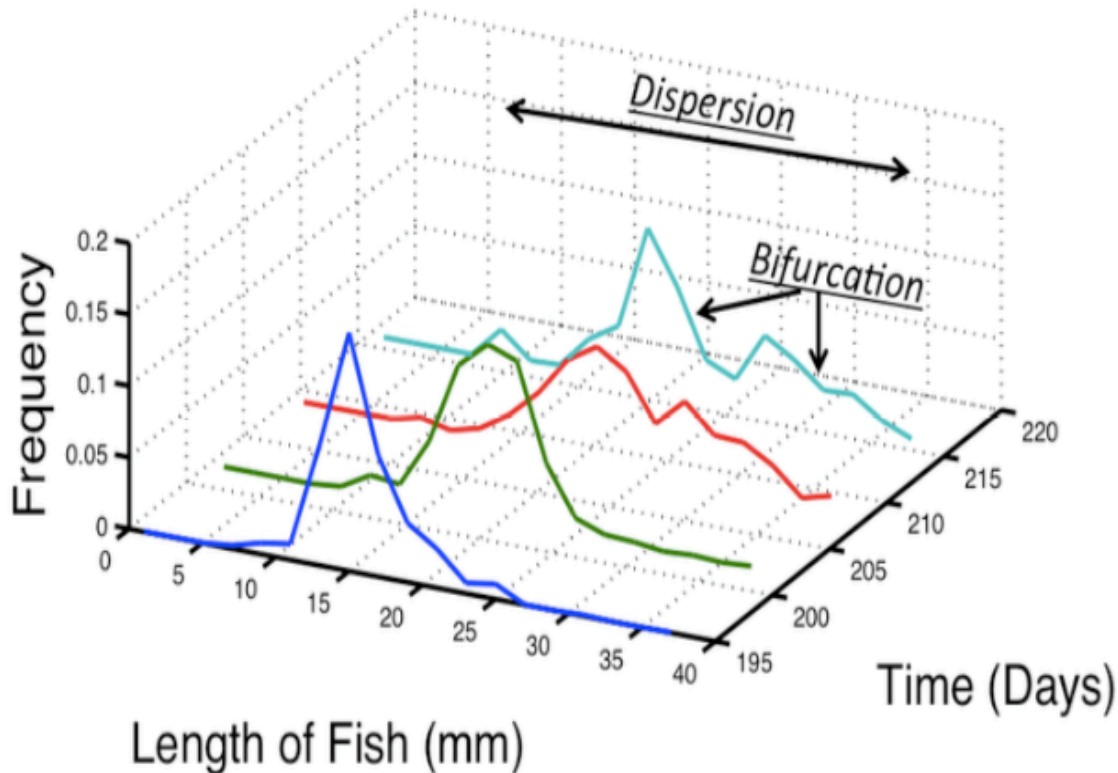


Source: Saunders, Nicholas A., et al. "Role of intratumoural heterogeneity in cancer drug resistance: molecular and clinical perspectives." *EMBO molecular medicine* 4.8 (2012): 675-684.

Incorporating heterogeneity in GBM Models

- Agent-based models
- Spatial models
- We can separate the tumor cell population into subpopulations:
 - ‘Go or grow’ in glioma growth
 - Androgen-dependent and androgen-independent cells in prostate cancer
 - Radio-sensitive and radio-resistant cells for treatment strategies
 - Oxidative-Phosphorylated cells and glycolytic cells

Random Differential Equations



Source: Banks, H. T. & Davis, J. L. A comparison of approximation methods for the estimation of probability distributions on parameters. *Appl. Numer. Math.* **57**, 753–777, (2007).

Dispersion and bifurcation features are not accounted for when using static parameters

Random Differential Equations

Consider the diffusion (\mathbf{D}) and growth (ρ) as random variables defined on a compact set $\Omega = \Omega_{\mathbf{D}} \times \Omega_{\rho}$

Model

$$\frac{\partial u(t, x, \mathbf{D}, \rho)}{\partial t} = \nabla \cdot (\mathbf{D} \nabla u(t, x, \mathbf{D}, \rho)) + \rho u(t, x, \mathbf{D}, \rho) (1 - u(t, x, \mathbf{D}, \rho))$$

Observation

$$\begin{aligned} u(t, x) &= \mathbb{E}[u(t, x, \cdot, \cdot), P] \\ &= \int_{\Omega} u(t, x, \mathbf{D}, \rho) dP(\mathbf{D}, \rho) \end{aligned}$$

Prohorov Metric Framework (PMF)

Idea: Using data, determine the approximate distributions of \mathbf{D} and $\boldsymbol{\rho}$, *without any underlying assumptions about the pdf/cdf*

$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left(\text{data}(t_j, x_i) - \int_{\Omega} u(t_j, x_i, \mathbf{D}, \boldsymbol{\rho}) dP(\mathbf{D}, \boldsymbol{\rho}) \right)^2$$

Prohorov Metric Framework Theory

Theorem

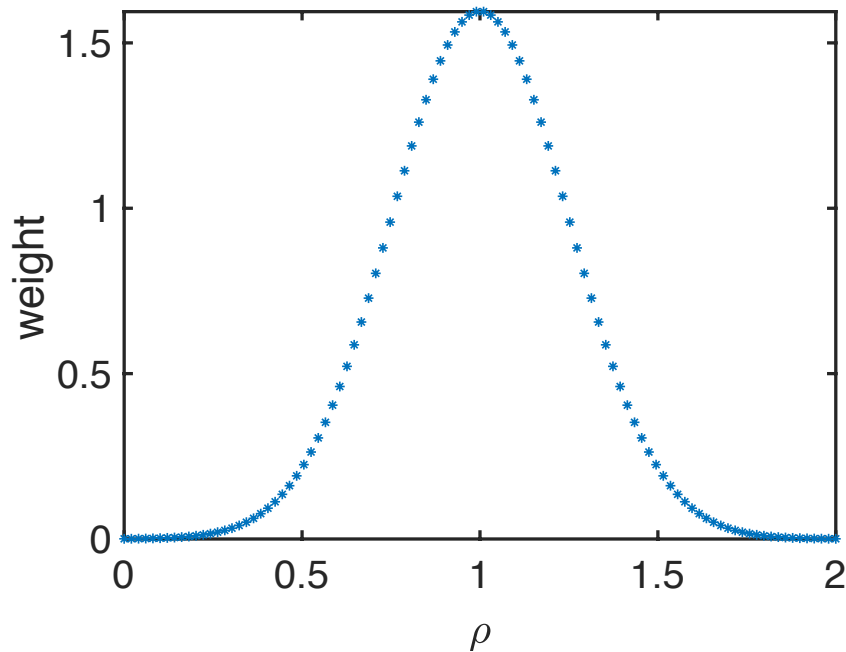
There exists a (not necessarily unique) minimizer \hat{P} (Banks, Hu, Thompson, 2015)

$$\hat{P} = \operatorname{argmin}_{P \in \mathcal{P}^M(\Omega)} \sum_{i,j} \left(\text{data}(t_j, x_i) - \int_{\Omega} u(t_j, x_i, \mathbf{D}, \boldsymbol{\rho}) dP(\mathbf{D}, \boldsymbol{\rho}) \right)^2$$

1. Since $\Omega = \Omega_{\mathbf{D}} \times \Omega_{\boldsymbol{\rho}}$ is a compact set, $\mathcal{P}(\Omega)$ is a compact metric space
 2. The minimizer is continuous in P
- \Rightarrow There exists a (not necessarily unique) minimizer

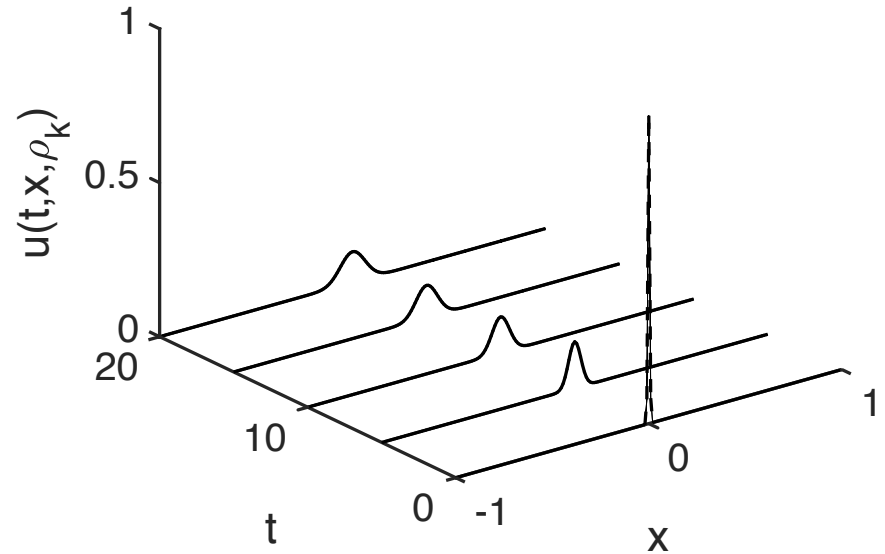
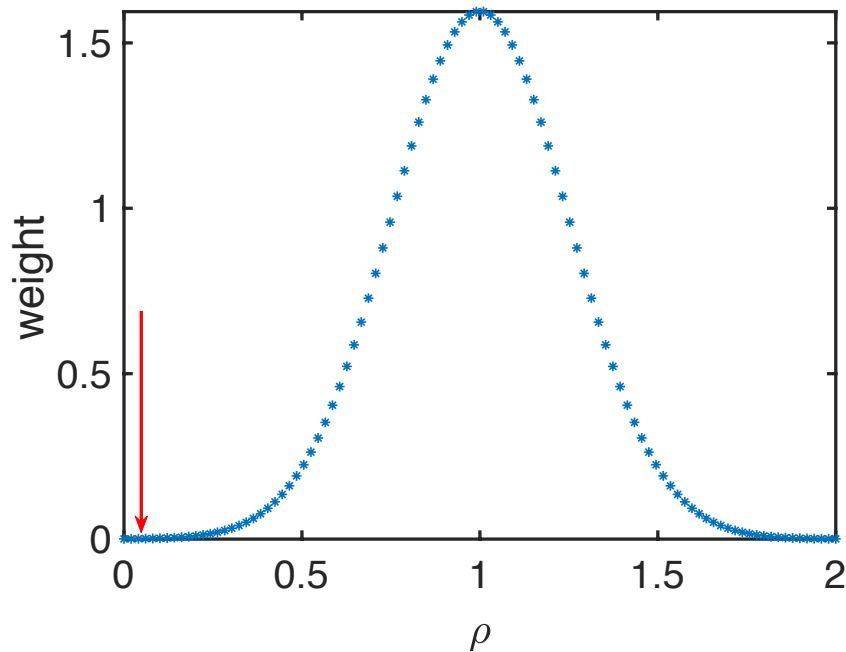
Creating Synthetic Data

We finely mesh over the parameter $\rho \in [0,2]$ and create our desired pdf



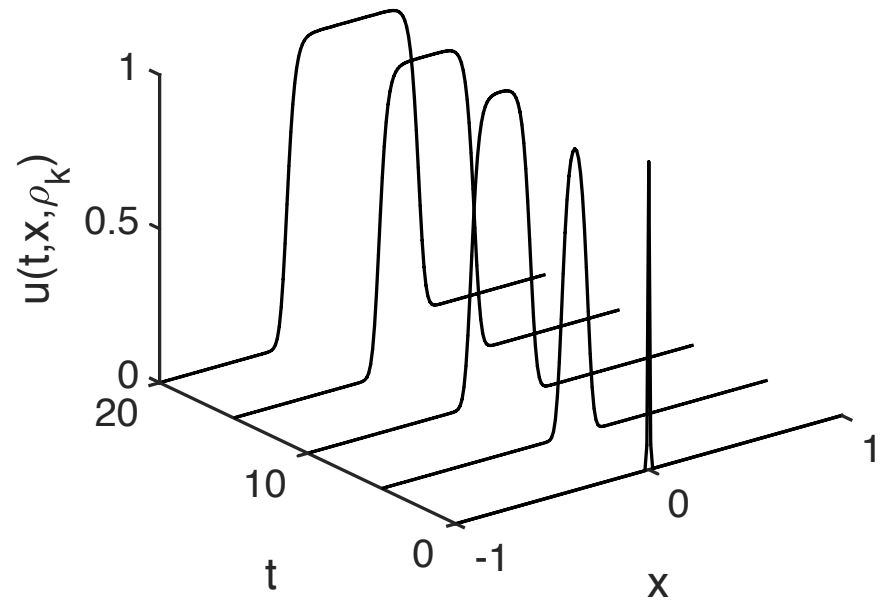
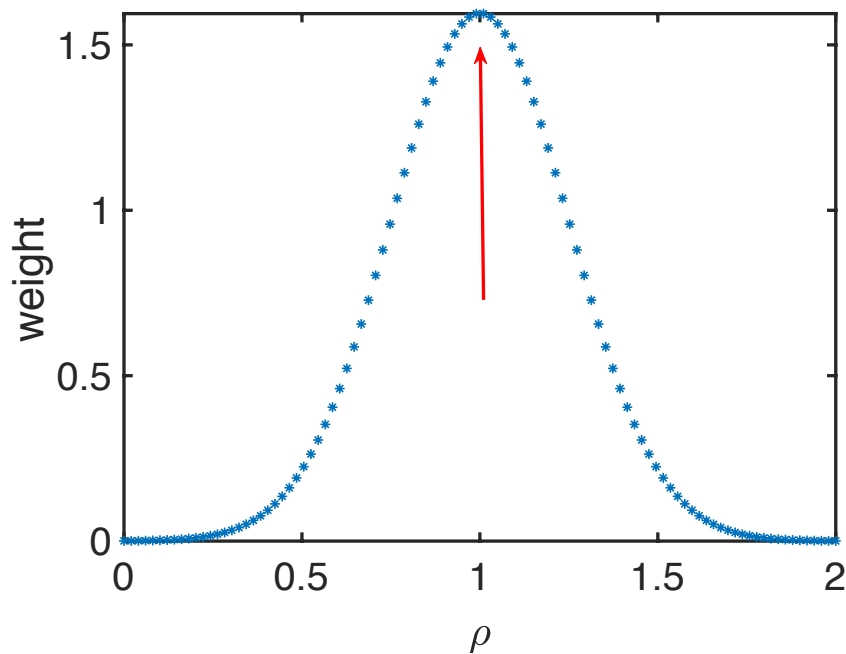
Creating Synthetic Data

$$\frac{\partial u(t, x, \rho_k)}{\partial t} = \nabla \cdot (D \nabla u(t, x, \rho_k)) + \rho_k u(t, x, \rho_k) (1 - u(t, x, \rho_k))$$



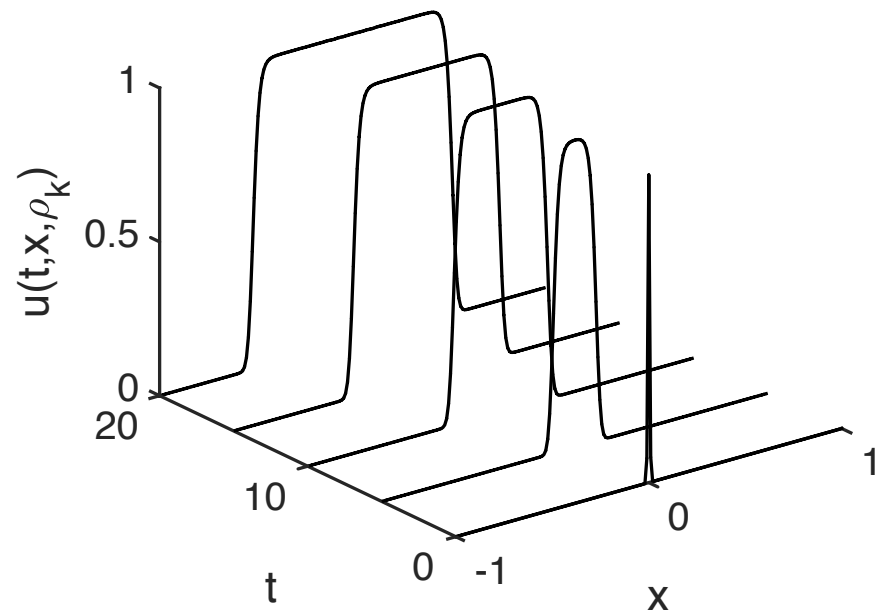
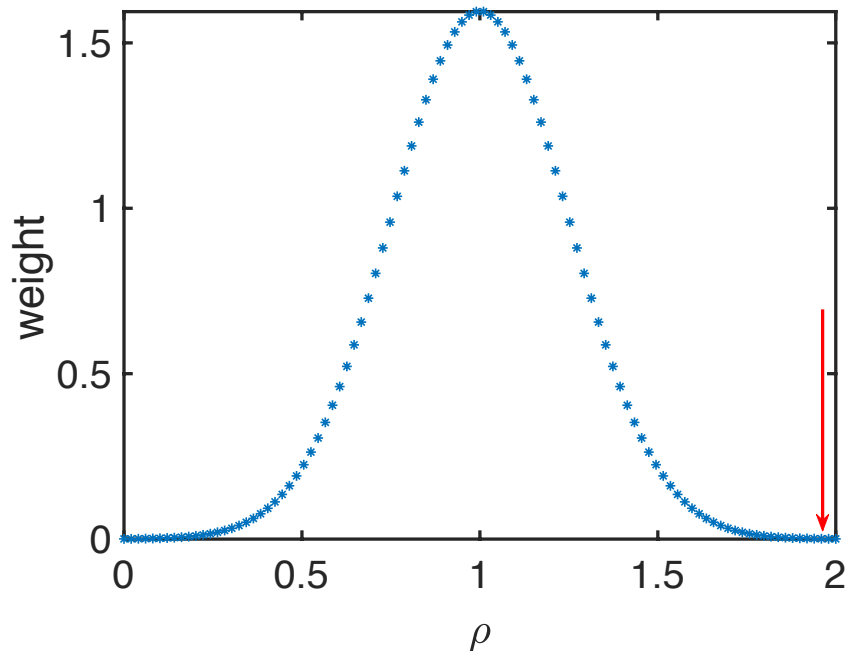
Creating Synthetic Data

$$\frac{\partial u(t, x, \rho_k)}{\partial t} = \nabla \cdot (D \nabla u(t, x, \rho_k)) + \rho_k u(t, x, \rho_k) (1 - u(t, x, \rho_k))$$

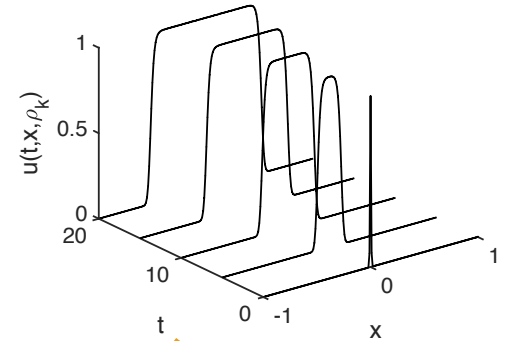
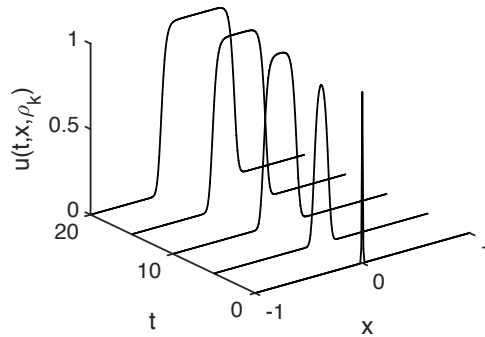
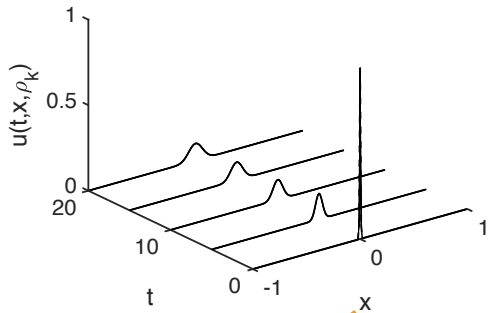


Creating Synthetic Data

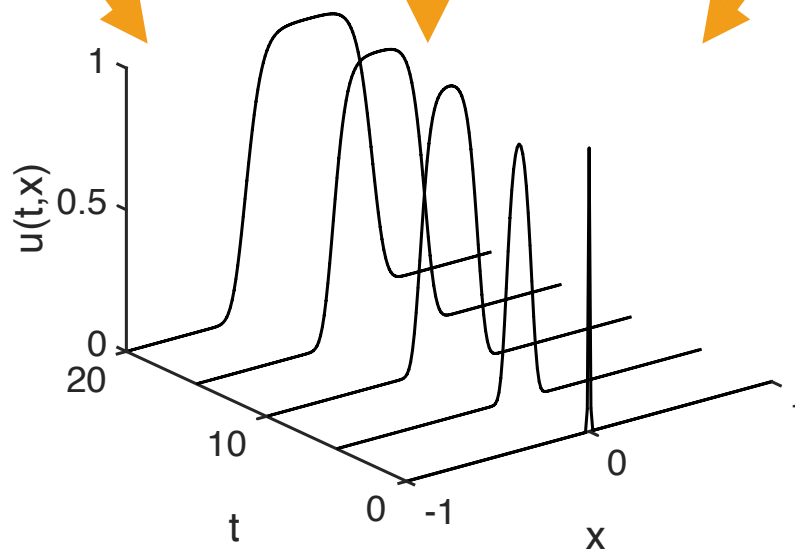
$$\frac{\partial u(t, x, \rho_k)}{\partial t} = \nabla \cdot (D \nabla u(t, x, \rho_k)) + \rho_k u(t, x, \rho_k) (1 - u(t, x, \rho_k))$$



Creating Synthetic Data

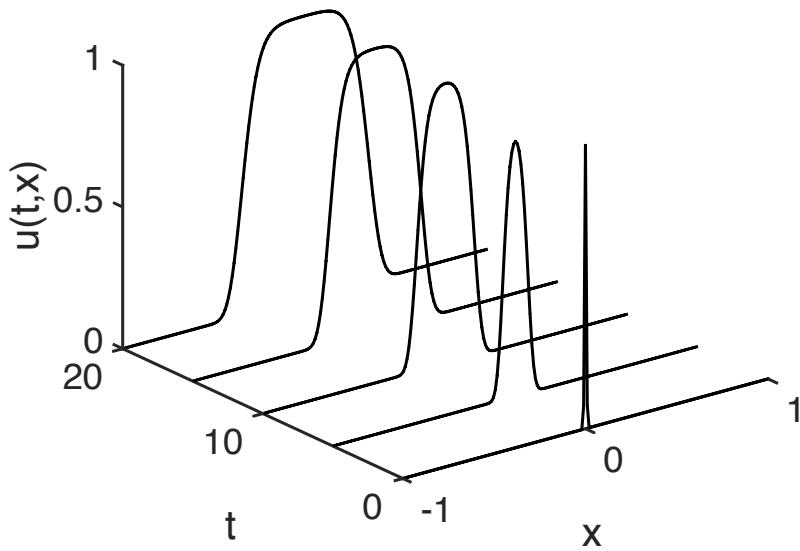


$$u(t, x) = \sum_{k=1}^N u(t, x, \rho_k) \omega_k$$

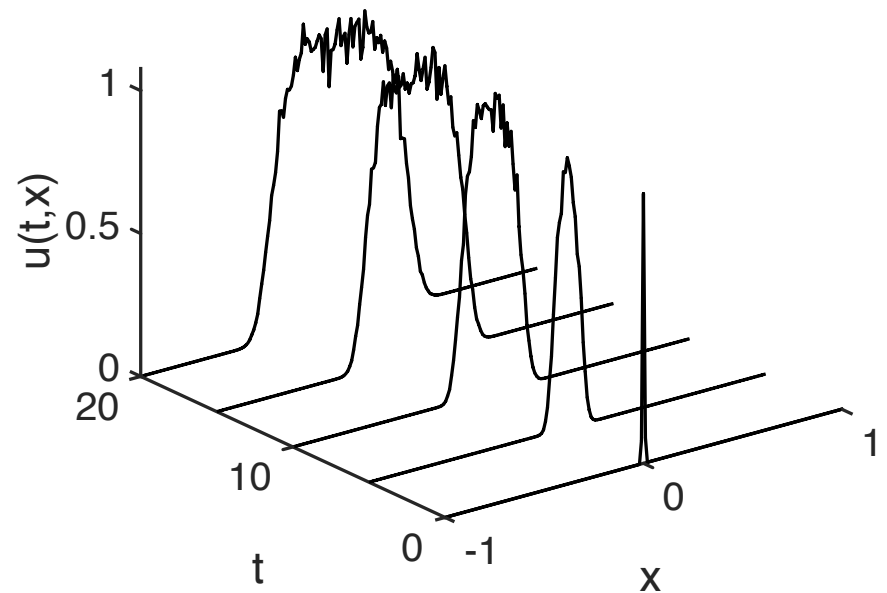


Creating Synthetic Data

$$\text{data}(t_j, x_i) = \text{sim}(t_j, x_i) + \varepsilon \text{sim}(t_j, x_i)$$
$$\varepsilon \sim 0.05N(0,1)$$



sim



data

Performing the Inverse Problem: Delta Functions

Assume there are M nodes equispaced over Ω_ρ such that $\boldsymbol{\rho}^M = \{\Delta_{\rho_k}, k = 1, \dots, M\}$

$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left[\text{data}(t_j, x_i) - \left(\sum_{k=1}^M u(t_j, x_i, D, \rho_k) \omega_k \right) \right]^2$$

where $\omega_k \geq 0$ represent a discrete probability density function. Thus, we require

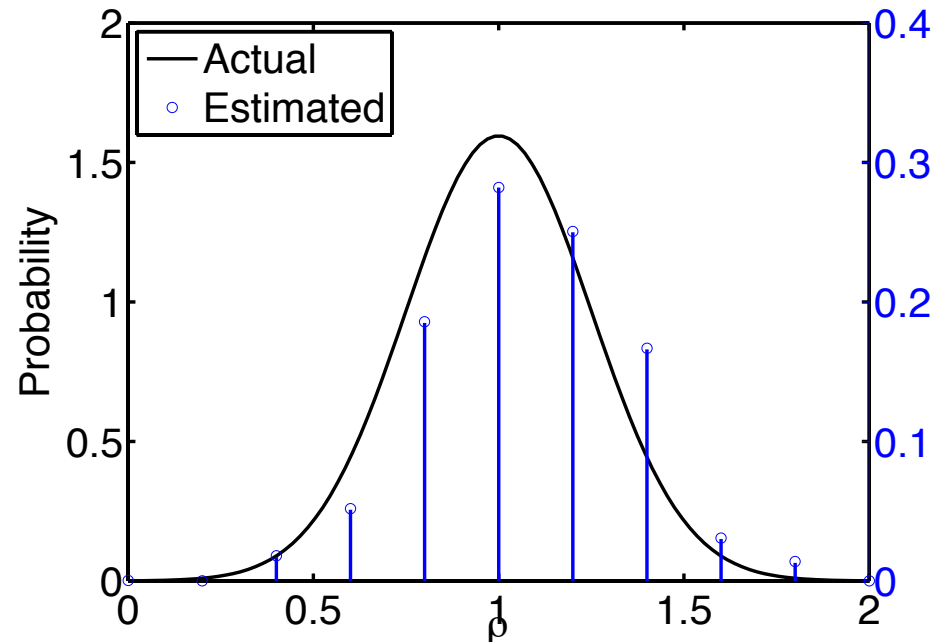
$$\sum_{k=1}^M \omega_k = 1$$

Performing the Inverse Problem: Delta Functions

$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left[\text{data}(t_j, x_i) - \left(\sum_{k=1}^M u(t_j, x_i, D, \rho_k) \omega_k \right) \right]^2$$

Example: we have $M=11$ nodes, equispaced over $[0,2]$ and we precompute $u(t, x, D, \rho_k)$

We are solving for the ω_k , the discrete weights



Performing the Inverse Problem: Spline Functions

Assume M nodes equispaced over Ω_ρ such that $\boldsymbol{\rho}^M = \{s_k(\boldsymbol{\rho}), k = 1, \dots, M\}$, where s_k are hat functions

$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left[\text{data}(t_j, x_i) - \left(\sum_{k=1}^M a_k \int_{\Omega_\rho} u(t_j, x_i, D, \boldsymbol{\rho}) s_k(\boldsymbol{\rho}) d\boldsymbol{\rho} \right) \right]^2$$

where $p_k = a_k s_k(\boldsymbol{\rho}) \geq 0$ represent a probability density function. Thus, we require

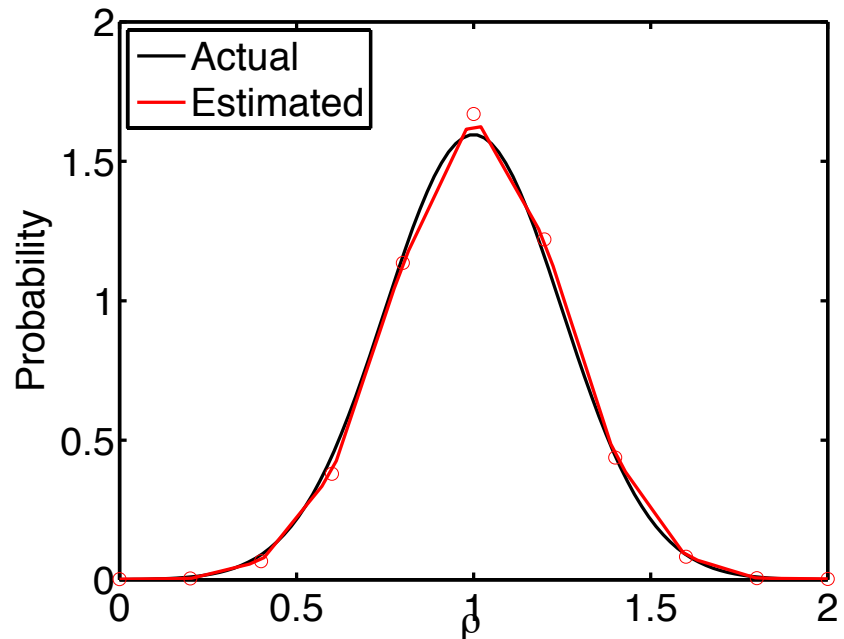
$$\sum_{k=1}^M a_k \int_{\Omega_\rho} s_k(\boldsymbol{\rho}) d\boldsymbol{\rho} = 1$$

Performing the Inverse Problem: Spline Functions

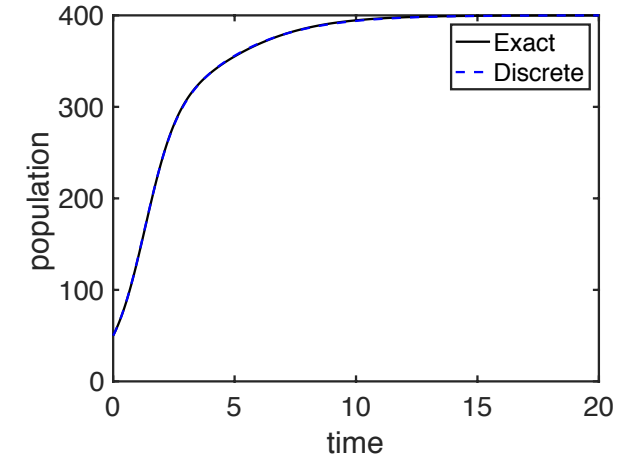
$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left[\operatorname{data}(t_j, x_i) - \left(\sum_{k=1}^M a_k \int_{\Omega_\rho} u(t_j, x_i, D, \rho) s_k(\rho) d\rho \right) \right]^2$$

Example: we have $M=11$ nodes, equispaced over $[0,2]$

We are solving for the a_k



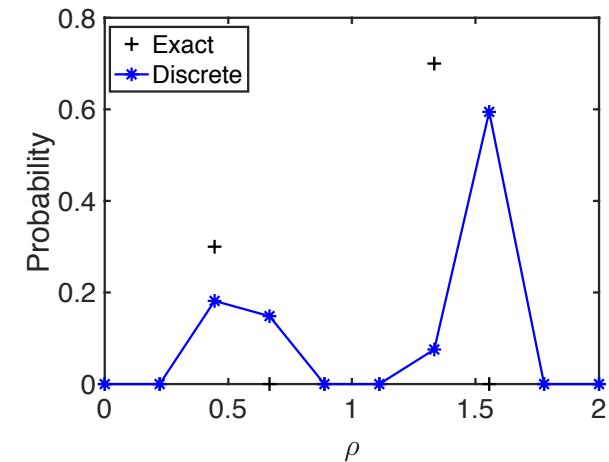
How to choose M: the optimal number of nodes?



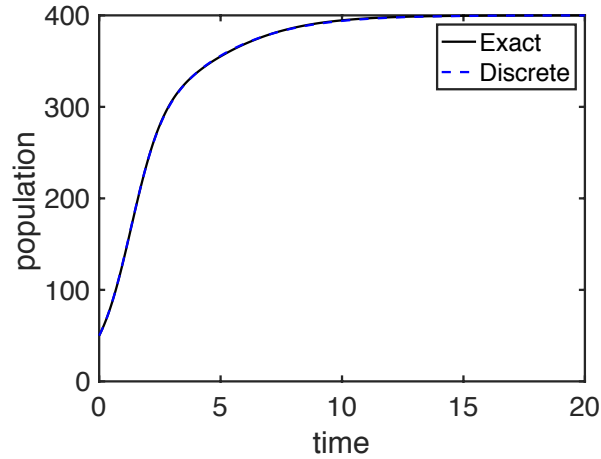
RSS = 875.8139



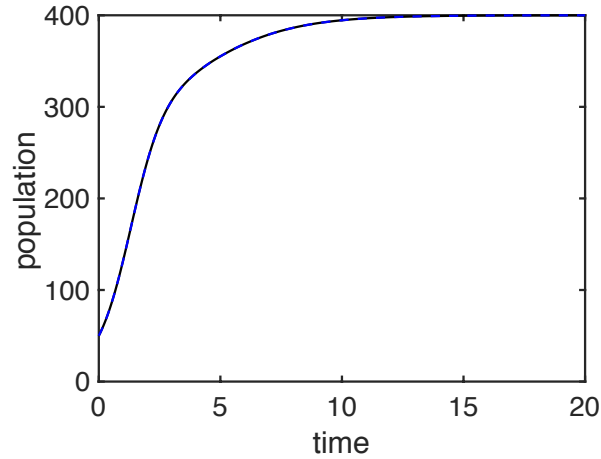
Increasing M: the number of nodes



How to choose M: the optimal number of nodes?



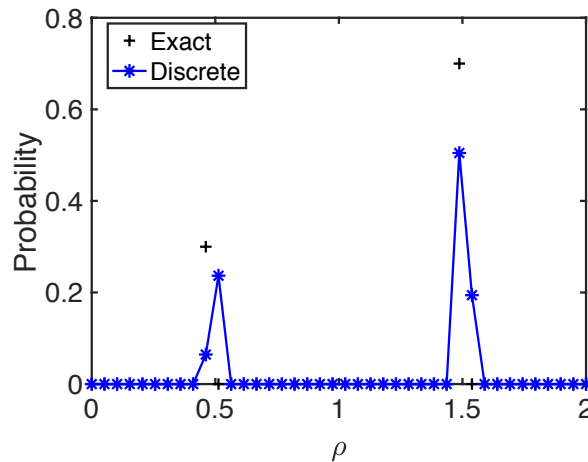
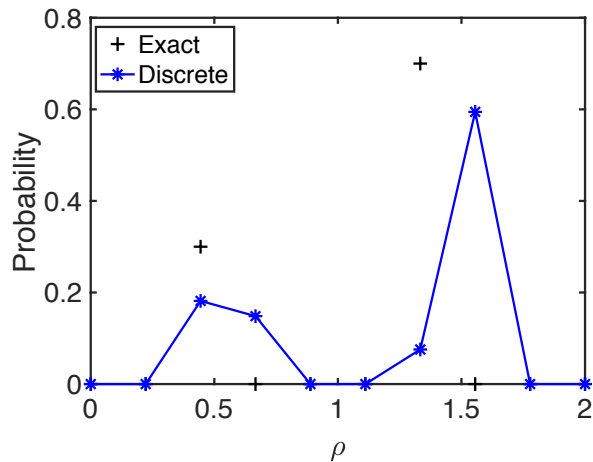
RSS = 875.8139



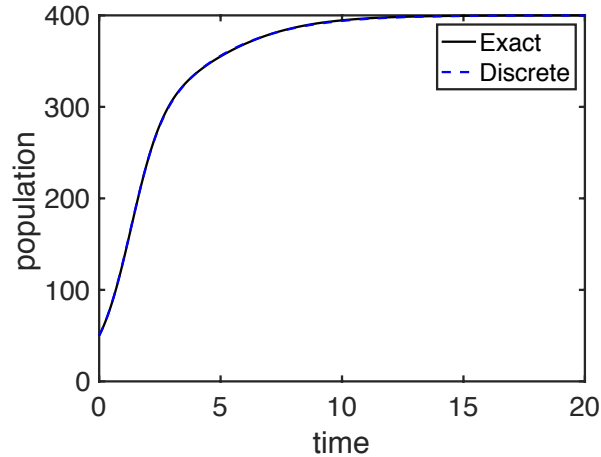
RSS = 3.6191



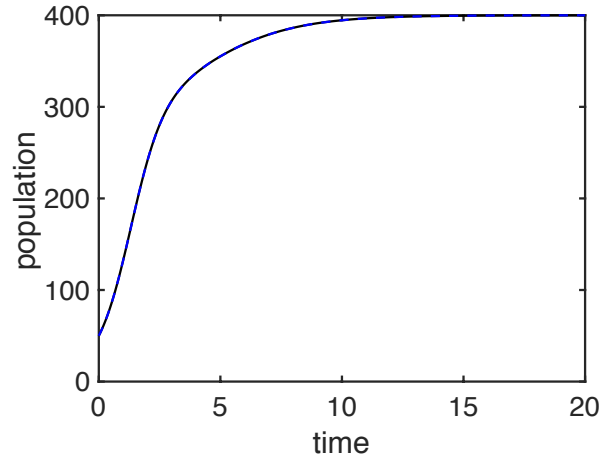
Increasing M: the number of nodes



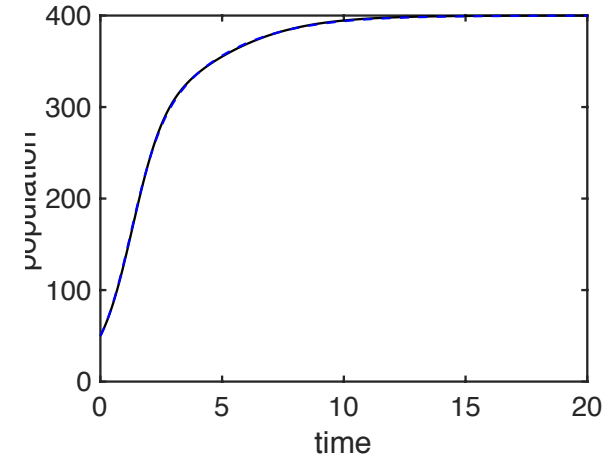
How to choose M: the optimal number of nodes?



RSS = 875.8139

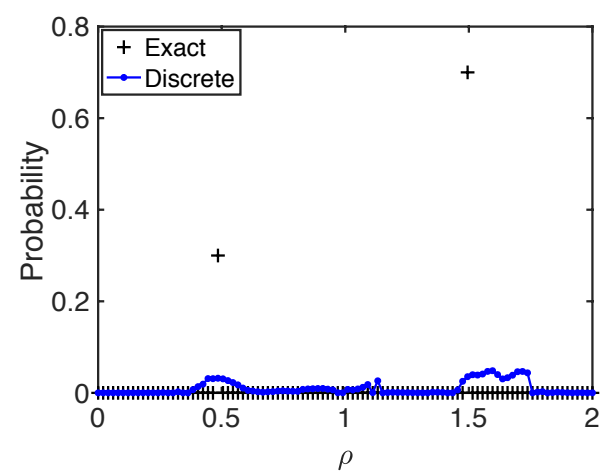
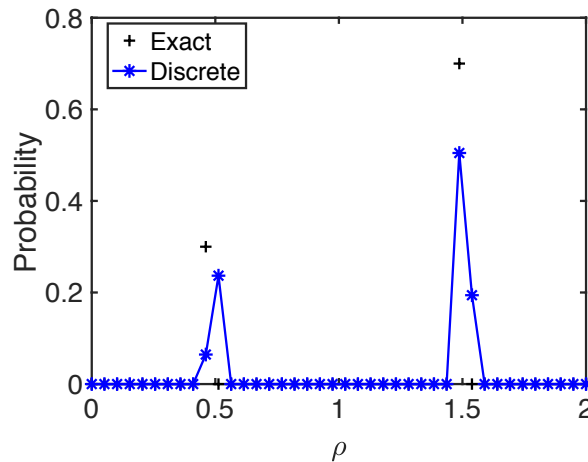
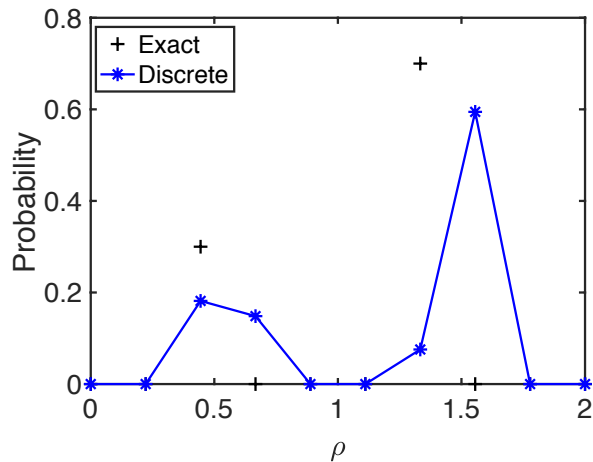


RSS = 3.6191



2.5656e+03

Increasing M: the number of nodes



How to choose M : the optimal number of nodes?

Akaike Information Criteria (AIC) as a model comparison test in the context of least-squares

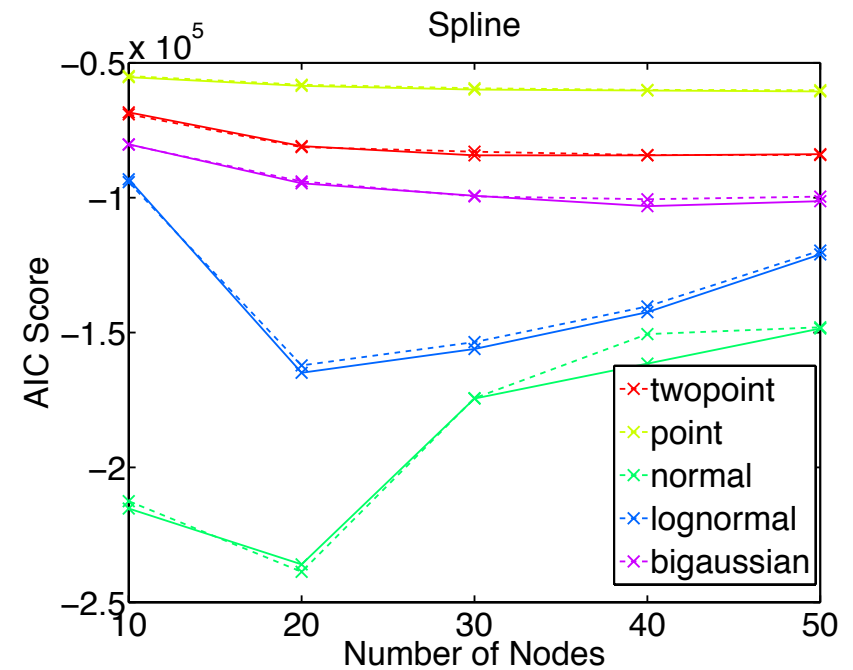
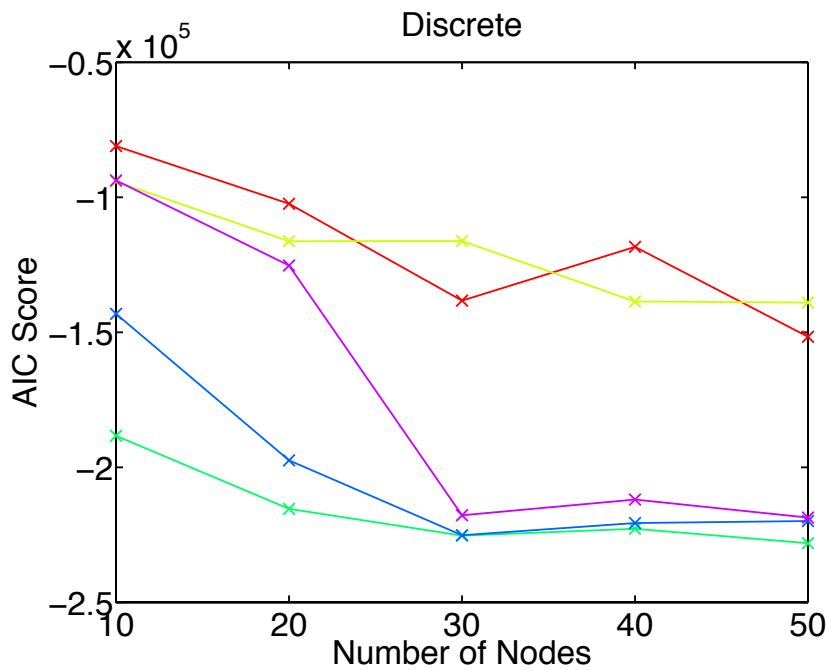
$$AIC = N \ln \left(\frac{\text{RSS}}{N} \right) + N(1 - \ln(2\pi)) + 2(M + 1)$$

N : number of data points

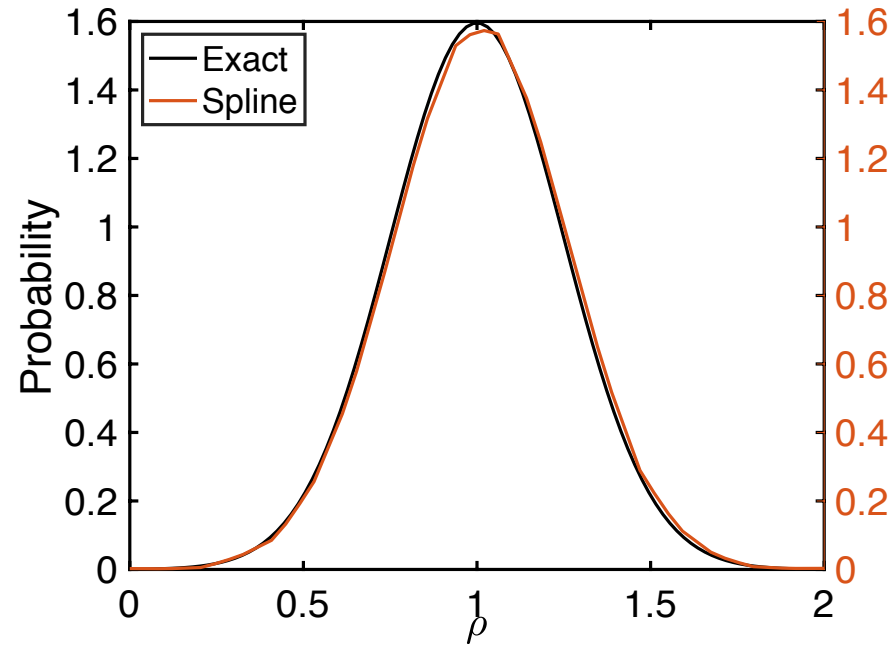
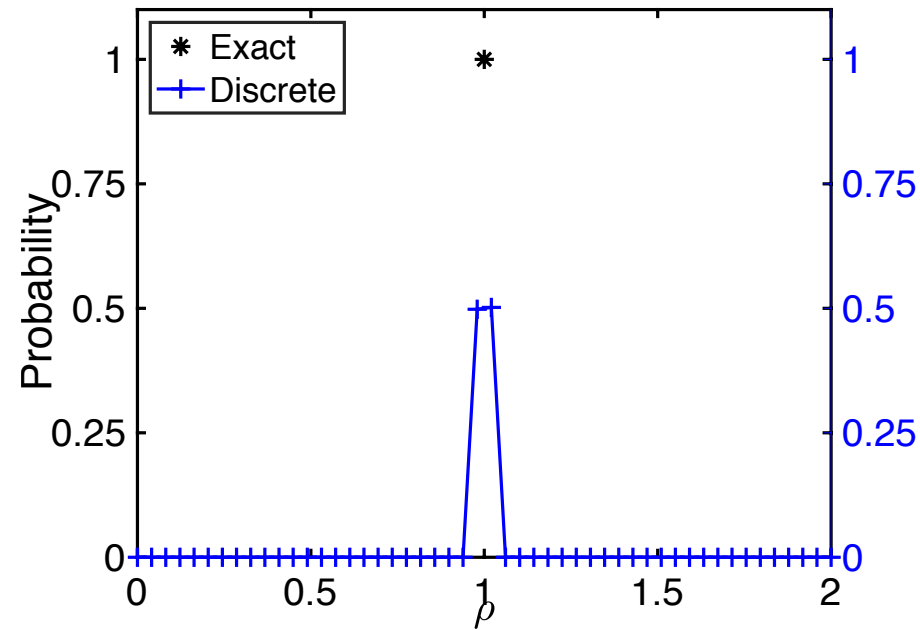
RSS: error between data and solution $u(t, x)$

M : number of parameters being fit (our M nodes)

How to choose M: the optimal number of nodes?



Representative Results: finding ρ



Performing the Inverse Problem: Delta Functions

Assume there are M_ρ nodes equispaced over Ω_ρ such that $\rho^M = \{\Delta_{\rho_k}, k = 1, \dots, M_\rho\}$ and that there are M_D nodes equispaced over Ω_D such that $D^M = \{\Delta_{D_l}, l = 1, \dots, M_D\}$

$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left[\text{data}(t_j, x_i) - \left(\sum_{l=1}^{M_D} \sum_{k=1}^{M_\rho} u(t_j, x_i, D_l, \rho_k) \omega_k \omega_l \right) \right]^2$$

where $\omega_k, \omega_l \geq 0$ represent a discrete probability density function. Thus, we require

$$\sum_{k=1}^{M_\rho} \omega_k = 1 \qquad \sum_{l=1}^{M_D} \omega_l = 1$$

Performing the Inverse Problem: Spline Functions

Assume M_ρ nodes equispaced over Ω_ρ such that $\boldsymbol{\rho}^{M_\rho} = \{s_k(\boldsymbol{\rho}), k = 1, \dots, M_\rho\}$, and M_D nodes equispaced over Ω_D such that $\mathbf{D}^{M_D} = \{s_l(\mathbf{D}), l = 1, \dots, M_D\}$, where s_k, s_l are hat functions

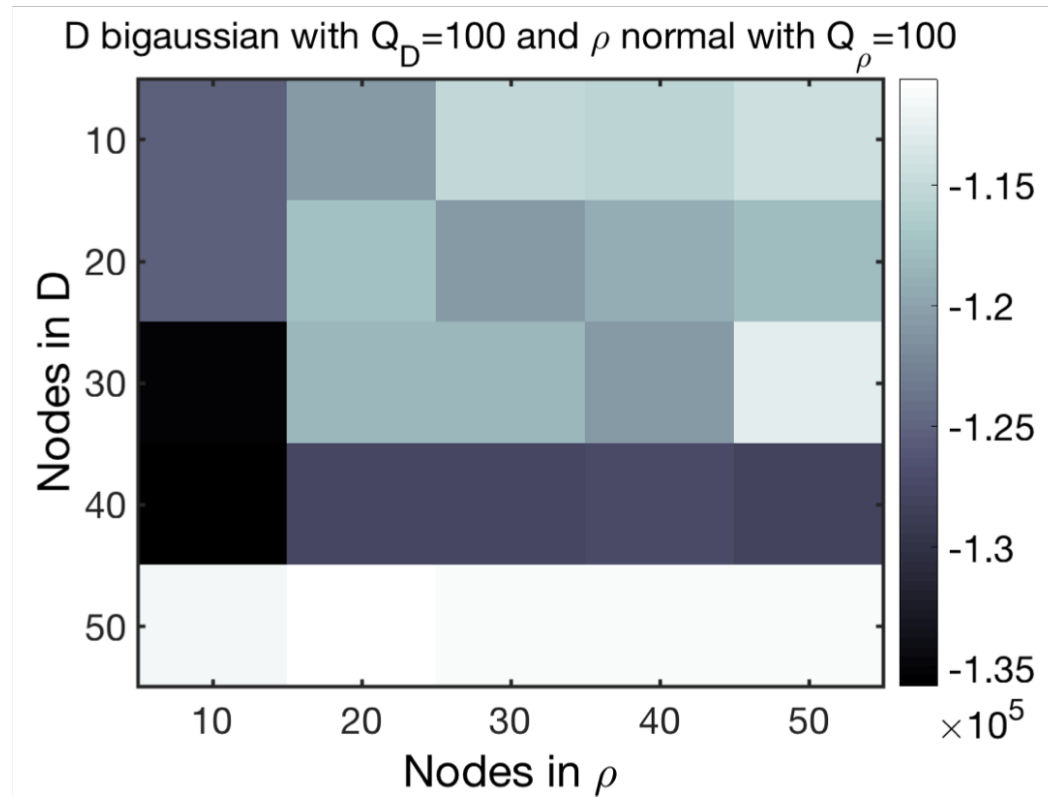
$$\hat{P} = \operatorname{argmin}_{P^M(\Omega)} \sum_{i,j} \left[\text{data}(t_j, x_i) - \sum_{l=1}^{M_D} a_l \int_{\Omega_D} \left(\sum_{k=1}^{M_\rho} b_k \int_{\Omega_\rho} u(t_j, x_i, \mathbf{D}, \boldsymbol{\rho}) s_l(\mathbf{D}) d\mathbf{D} \right) s_k(\boldsymbol{\rho}) d\boldsymbol{\rho} \right]^2$$

where $p_k = b_k s_k(\boldsymbol{\rho}) \geq 0$, $p_l = a_l s_l(\mathbf{D}) \geq 0$
represent probability density functions.

$$\sum_{k=1}^{M_\rho} b_k \int_{\Omega_\rho} s_k(\boldsymbol{\rho}) d\boldsymbol{\rho} = 1$$

$$\sum_{l=1}^{M_D} a_l \int_{\Omega_D} s_l(\mathbf{D}) d\mathbf{D} = 1$$

Selection of M



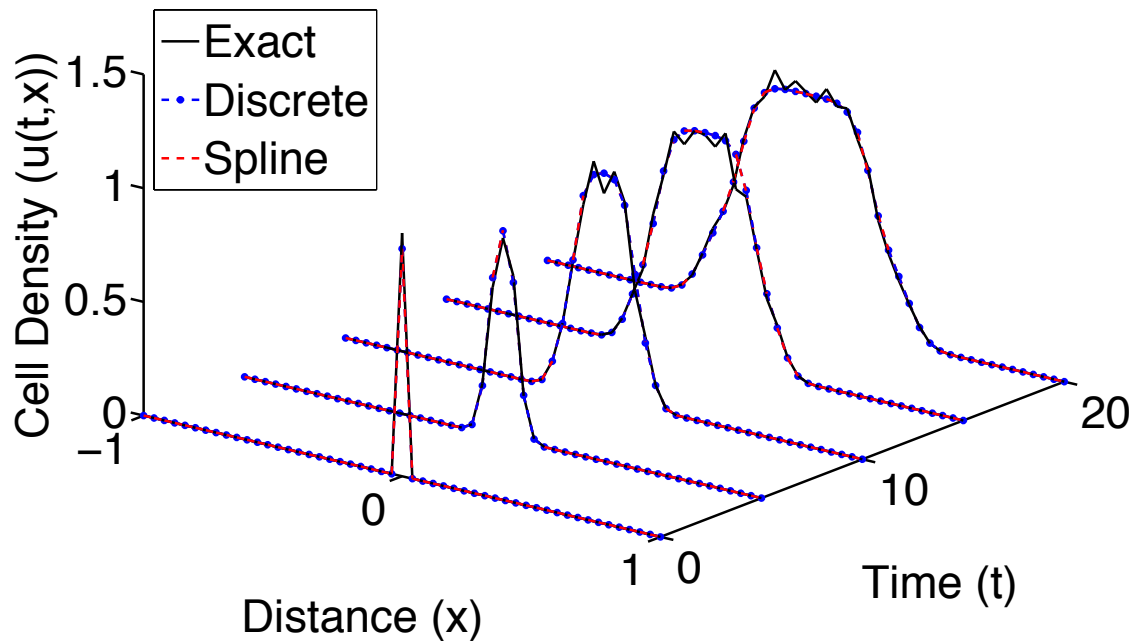
Representative Results

ρ normally distributed and \mathbf{D} bigaussian

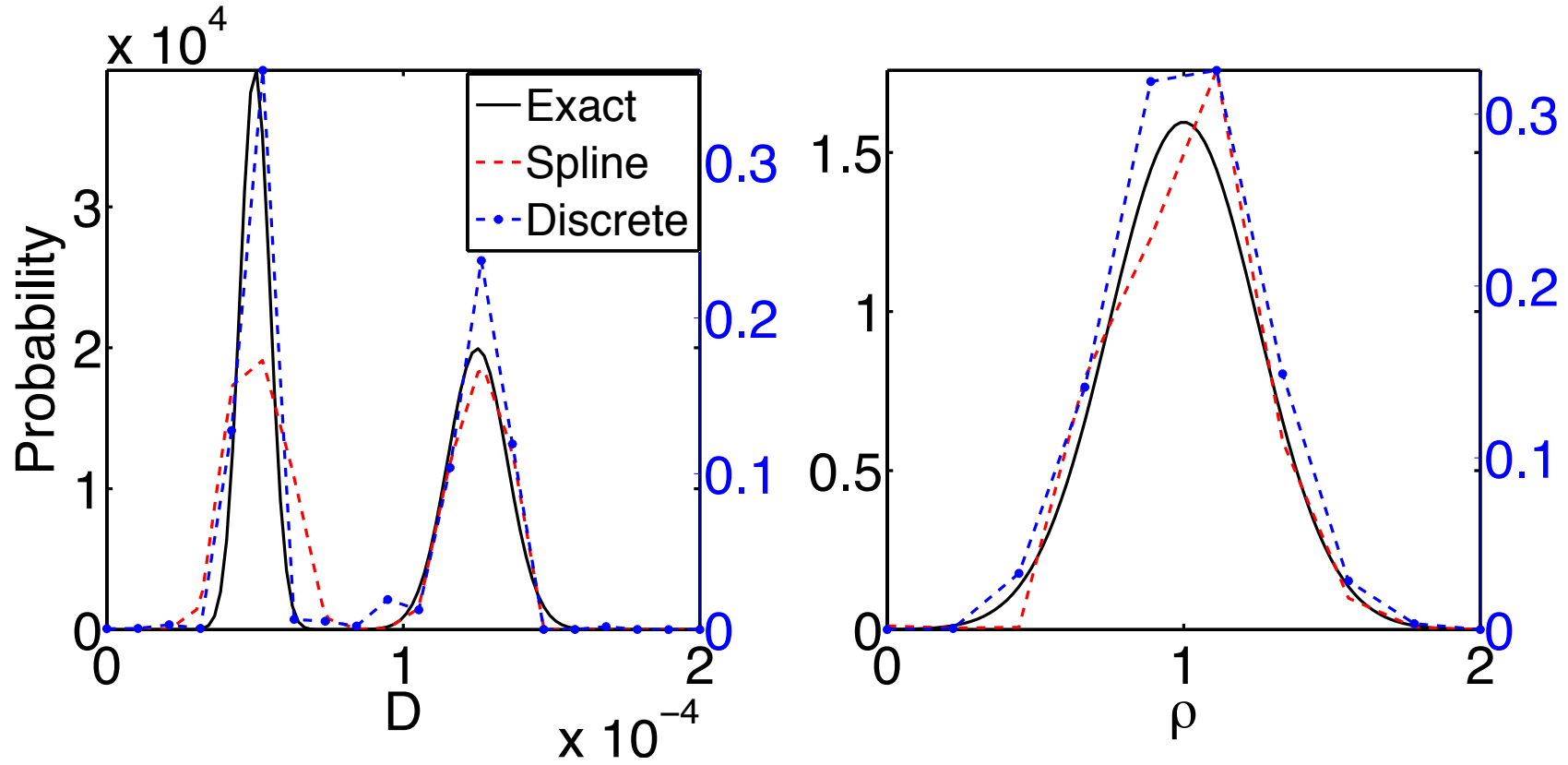
Goal: Recover parameter distributions

$$\text{data}(t_j, x_i) = \text{sim}(t_j, x_i) + \varepsilon \text{sim}(t_j, x_i)$$

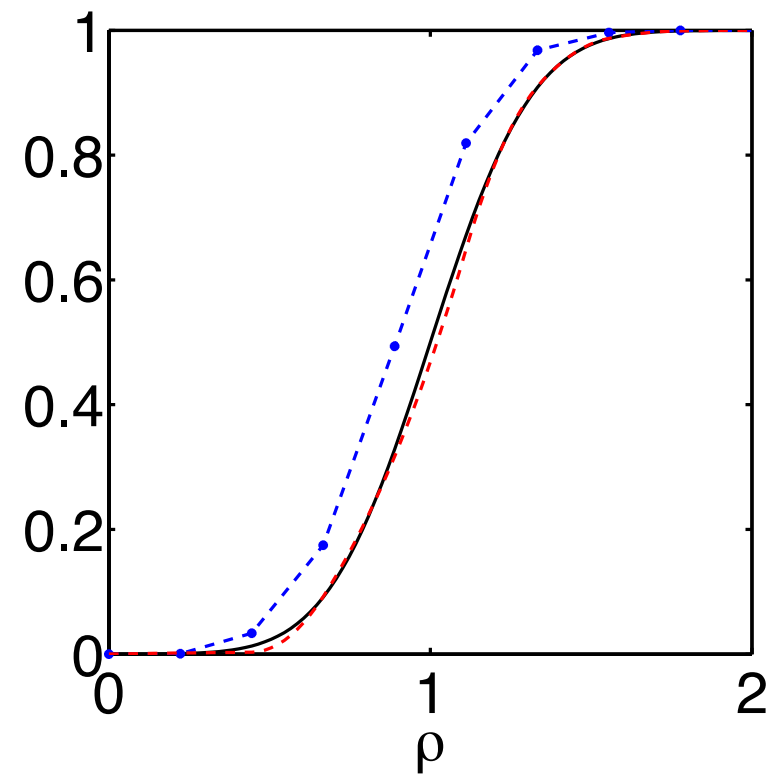
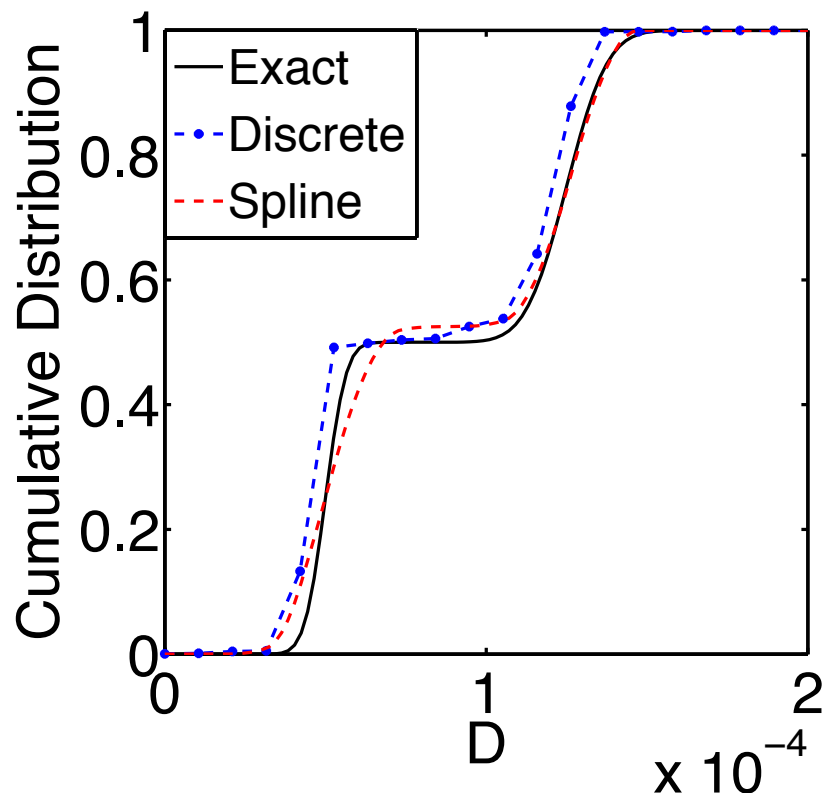
$$\varepsilon \sim 0.05N(0,1)$$



Resulting pdf Estimates



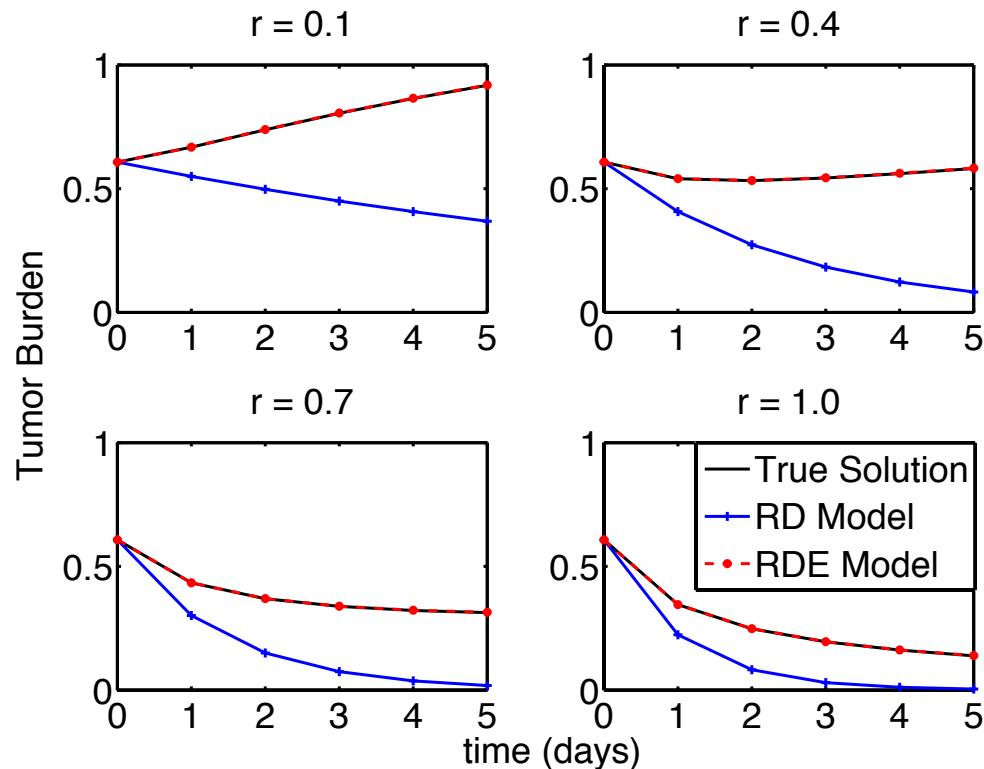
Resulting cdf Estimates



Treatment Prediction Assuming Heterogeneity

Assuming a log-kill hypothesis, we add the term:

$$-r \frac{\rho}{\bar{\rho}} u(t, x)$$

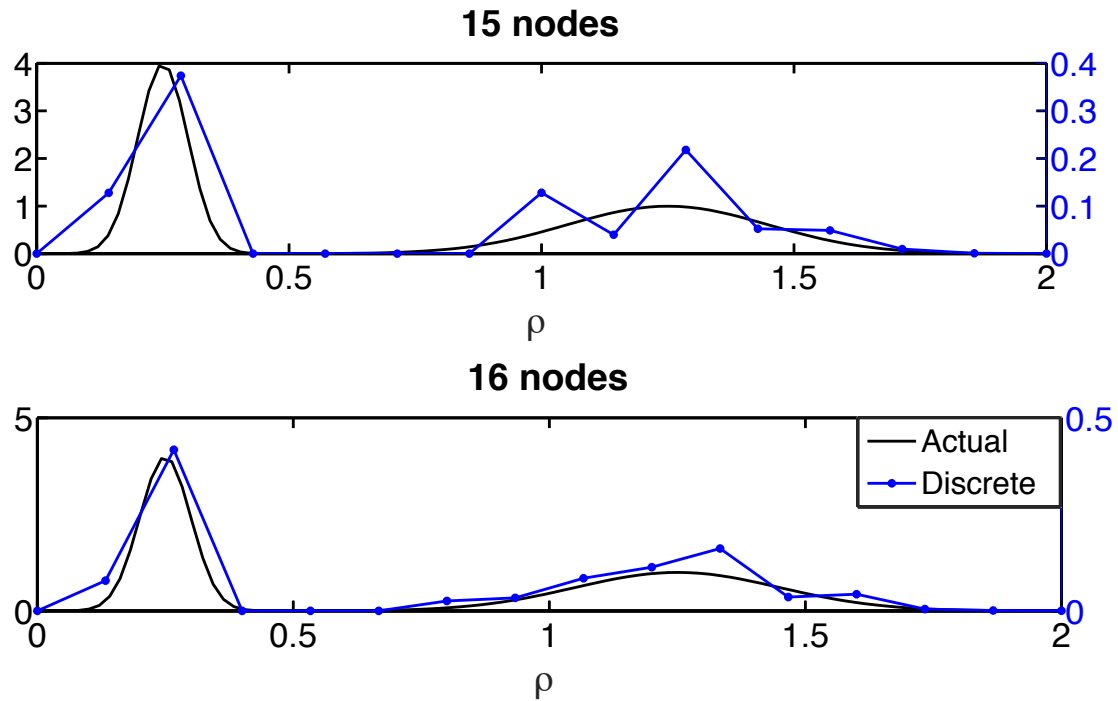


Conclusions

- We can recover parameter distributions from spatiotemporal data from a variety of pdfs
- Assuming cellular homogeneity may result in overestimating treatment efficacy
- However, there remain many questions to be answered...

Future Projects

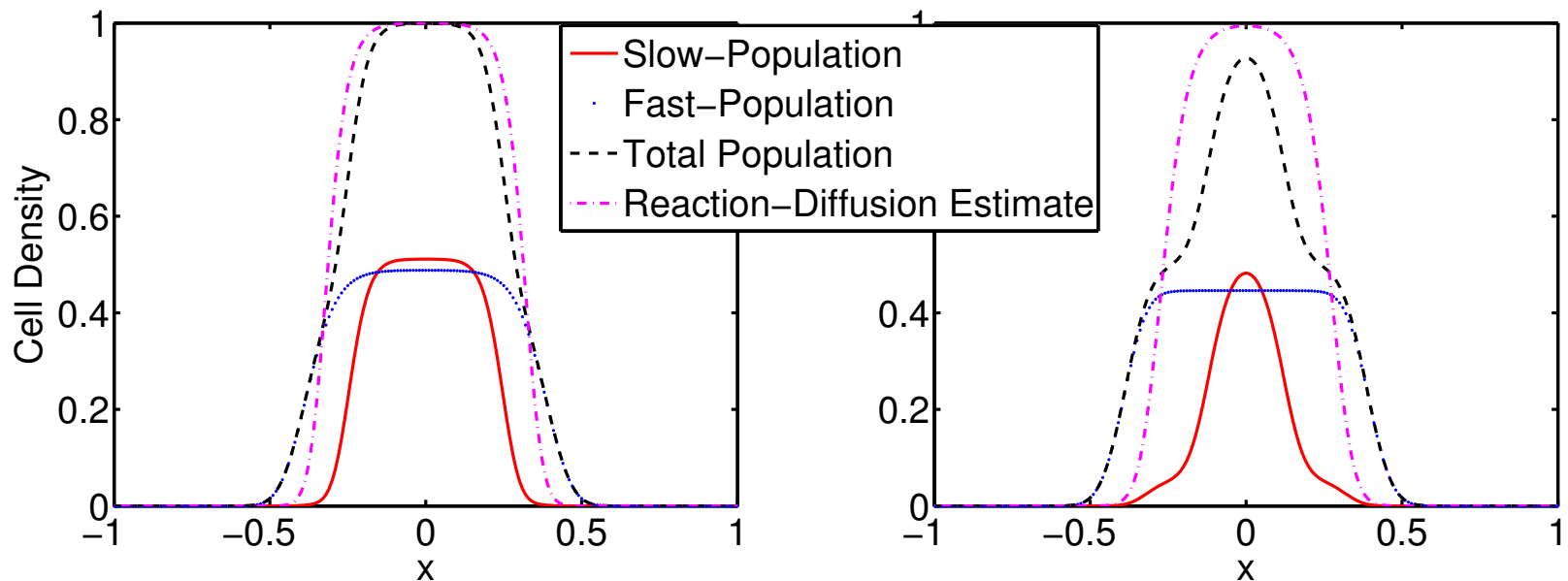
1. Adaptive meshing of nodes



Future Projects

2. Rewrite to consider carrying capacity on total population

$$\frac{\partial u(t, x, \rho_k)}{\partial t} = \nabla \cdot (D \nabla u(t, x, \rho_k)) + \rho_k u(t, x, \rho_k) \left(1 - \sum_{k=1}^M u(t, x, \rho_k) \right)$$



Future Projects

3. Uncertainty quantification/sensitivity analysis of resulting parameter distributions
4. How much data is needed to recover distributions?
5. Use the framework to model and estimate
 - Metabolic heterogeneity
 - Heterogeneity in therapy resistance
 - Androgen sensitivity in prostate cancer cells
6. Fit to *in vitro* or *in vivo* data
7. Extend framework to deal with 2D and 3D space

Thank you for your attention!

Questions?